

# Knowledge Representation and Reasoning

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# Lectures: Where, When, Webpage

## Where

Lecture hall 52-02-017

## When

Mon: 11:15–13:00, Wed: 11:15–12:00 (+ exercises)

## Christmas break

Last lecture before Christmas: Wed, Dec 21

First lecture after Christmas: Mon, Jan 9

## Web page

<http://www.informatik.uni-freiburg.de/~ki/teaching/ws0506/krr/>

# Lecturers

## Prof Dr. Bernhard Nebel

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Consultation: Tuesday 14:00-15:00 and by appointment

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## Dr. Stefan Wölfel

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# Exercises I

## Where

Lecture hall 52-02-017

## When

Wed, 12:05-12:50

## Exercise assistant: Malte Helmert

Room 52-00-030, Phone: 0761/203-8225  
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## Exercise assistant: Marco Ragni

Room 52-00-023, Phone: 0761/203-8252  
email: ragni@informatik.uni-freiburg.de

## Exercises II

- ▶ Exercises will be given at the web page on Wednesdays. (However, first exercise on Wed, Nov 2.)
- ▶ Solutions can be given in English and German.
- ▶ Students can work in pairs and hand in one solution.
- ▶ Larger groups and copied results will not be accepted.
- ▶ Previous week's exercises have to be handed in before the lecture on Monday.

# Examination & Schein

- ▶ A written examination takes place in the semester pause.
- ▶ The examination is obligatory for *ACS Master* students.
- ▶ Grade:
  - ▶ max 100 points from the exam
  - ▶ max 10 bonus points from exercises
  - ▶ max 10 bonus points from projects (programming exercises)

# Course Prerequisites & Goals

## Goals

- ▶ Acquiring skills in representing knowledge
- ▶ Understanding the principles behind different knowledge representation techniques
- ▶ Being able to read and understand research literature in the area of KR&R
- ▶ Being able to complete a project in this research area

## Prerequisites

- ▶ Basic knowledge in the area of AI
- ▶ Basic knowledge in formal logic
- ▶ Basic knowledge in theoretical computer science

# AI and Knowledge Representation

- ▶ **AI** can be described as: The study of **intelligent behavior** achieved through **computational means**
- ▶ **Knowledge representation and reasoning** could then be viewed as the study of how to **reason** (compute) with **knowledge** in order to decide what to do.
- ▶ Before we can start reasoning with knowledge, we have to **represent** it.

# Knowledge

- ▶ We understand by “knowledge” all kinds of facts about the world.
- ▶ Knowledge is necessary for intelligent behavior (human beings, robots).
- ▶ What is knowledge? We shall not try to answer this question!
- ▶ Instead, in this course we consider “representations of knowledge”.

# Representation

- ▶ If **A** represents **B**, then **A** stands for **B** and is usually more easily accessible than **B**.
- ▶ In our case we are interested in **groups of symbols** that stand for some **proposition**.

## Knowledge Representation

The field of study concerned with **representations** of propositions (that are believed by some agent)

# Reasoning

- ▶ **Reasoning** is the use of representations of propositions in order to derive new ones.
- ▶ While propositions are abstract objects, their representations are concrete objects and can be easily manipulated.
- ▶ Reasoning can be as easy as arithmetics  $\rightsquigarrow$  mechanical symbol manipulation.
- ▶ For example:
  - ▶ raining is true
  - ▶ IF raining is true THEN wet street is true
  - ▶ wet street is true

# Why is Knowledge Representation and Reasoning Useful?

- ▶ Describing/understanding the behavior of systems in terms of the knowledge it has.
- ▶ Generating the behavior of a system!
  - ▶ Declarative knowledge can be separated from its possible usages. (compare: procedural knowledge)
  - ▶ Understanding the behavior of an intelligent system in terms of the represented knowledge makes debugging and understanding much easier.
  - ▶ Modifications and extensions are also much easier to perform.

# Knowledge-Based Systems: An Example

```
printC(snow) :- !, write("It's white").
printC(grass) :- !, write("It's green").
printC(sky) :- !, write("It's yellow").
printC(X) :- !, write("Beats me").
```

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```
printC(X) :- color(X,Y), !, write("It's "), write(Y).
printC(X) :- write("Beats me").
color(snow,white).
color(sky,yellow).
color(X,Y) :- madeof(X,Z), color(Z,Y).
madeof(grass,vegetation).
color(vegetation,green).
```

# Advantages of Knowledge-Based Systems

- ▶ Why not use the first variant of the Prolog program?
- ▶ We can add new tasks and make them depend on previous knowledge.
- ▶ We can extend existing behavior by adding new facts.
- ▶ We can easily explain and justify the behavior.

# Why Reasoning?

- ▶ Note: there was no **explicit** statement about the color of grass in the program.
- ▶ In general: many facts will be there only **implicitly**.
- ▶ Use concept of **entailment/logical implication**.
- ▶ Can/shall we compute all implicit (all entailed) facts?
- ▶ It may be computationally too expensive.

# The Role of Formal Logic

- ▶ Formal logic is the field of study of entailment relations, formal languages, truth conditions, semantics, and inference.
- ▶ All propositions are represented as formulae which have a semantics according to the logic in question.
- ▶ Formal logics gives us a framework to discuss different kinds of reasoning.

# Different Kinds of Reasoning

- ▶ Usually, we are interested in deriving implicit, entailed facts from a given collection of explicitly represented facts
  - ▶ in a **logically sound** (the derived proposition must be true, given that the premises are true)
  - ▶ and **complete** way (all true consequences can be derived)
- ▶ Sometimes, however, we want logically unsound derivations (e.g. reasoning based on assumptions.)
- ▶ Sometimes, we want to give up completeness (e.g. for efficiency reasons.)

# Model-Finding and Satisfiability

- ▶ In planning and configuration tasks, we often get a set of **constraints** and a goal specification. We then have to find a solution satisfying all the constraints.
  - ▶ Either round or square
  - ▶ Either red or blue
  - ▶ If red and round or if blue and square then wood
  - ▶ If blue then metallic
  - ▶ If square then not metallic
  - ▶ If red then square
  - ▶ square

One solution: square, not metallic, red, wood

- ▶ Does not logically follow, but is one possible assignment (or model).

# Abduction: Inference to the Best Explanation

- ▶ In diagnosis tasks, we often have to find a good **explanation** for a given **observation** or **symptom**.
- ▶ Given a background theory, a set of explanations and an observation, find the **most likely set of explanations**.
  - ▶ earthquake **implies** alarm
  - ▶ burglar **implies** alarm
  - ▶ { earthquake, burglar } is the set of abducibles
  - ▶ alarm is observed
  - ▶ One explanation is earthquake ...
- ▶ There can be many possible explanations.
- ▶ Not a sound inference

# Default Reasoning: Jumping to Conclusions

- ▶ Often we do not have enough information, but nevertheless want to reach a conclusion (that is likely to be true).
- ▶ In the absence of evidence to the contrary, we **jump to a conclusion**.
  - ▶ Birds are usually able to fly.
  - ▶ Tweety is a bird.
  - ▶ So, you would expect that Tweety is able to fly.
- ▶ Unsound conclusion
- ▶ It might be necessary to withdraw conclusions when evidence to the contrary becomes available  $\rightsquigarrow$  nonmonotonic reasoning.

# The Role of Complexity Theory (1)

- ▶ Intelligent behavior is based on a vast amount of knowledge: Reddy's (1988) estimate is 70000 knowledge "units".
- ▶ Because of the huge amount of knowledge we have represented, reasoning should be easy in the complexity theory sense.
- ▶ Reasoning should **scale** well: we need efficient reasoning algorithms.

## The Role of Complexity Theory (2)

Use complexity theory and recursion theory to

- ▶ determine the complexity of reasoning problems,
- ▶ compare and classify different approaches based on complexity results,
- ▶ identify easy (polynomial-time) special cases,
- ▶ use heuristics/approximations for provably hard problems, and
- ▶ choose among different approaches.

# Course Outline

1. Introduction
2. Reminder: Classical Logic
3. A New Logic: Boxes and Diamonds
4. Nonmonotonic Logics
5. Qualitative Spatial and Temporal Reasoning
6. Description Logics

# Literature I

- ▶ R. J. Brachman and Hector J. Levesque, *Knowledge Representation and Reasoning*, unpublished manuscript.
- ▶ C. Beierle and G. Kern-Isberner, *Methoden wissensbasierter Systeme*, Vieweg, 2000.
- ▶ G. Brewka, ed., *Principles of Knowledge Representation*, CSLI Publications, 1996.
- ▶ G. Lakemeyer and B. Nebel (eds.), *Foundations of Knowledge Representation and Reasoning*, Springer-Verlag, 1994
- ▶ W. Bibel *Wissensrepräsentation und Inferenz*, Vieweg, 1993
- ▶ R. J. Brachman and Hector J. Levesque (eds.), *Readings in Knowledge Representation*, Morgan Kaufmann, 1985.
- ▶ B. Nebel, “Logics for Knowledge Representation,” in: N. J. Smelser and P. B. Baltes (eds.), *International Encyclopedia of the Social and Behavioral Sciences*, Kluwer, Dordrecht, 2001.

## Literature II

- ▶ B. Nebel, “Artificial Intelligence: A Computational Perspective” in G. Brewka, ed., *Principles of Knowledge Representation, Studies in Logic, Language and Information*, CSLI Publications, 1996, 237-266.
- ▶ *Proceedings of the International Conference on Principles of Knowledge Representation and Reasoning*, (1989, 1991, 1992, . . . , 2002, 2004), Morgan Kaufmann Publishers.