

# Knowledge Representation and Reasoning

Bernhard Nebel    Jussi Rintanen    Stefan Wölfel

Albert-Ludwigs-Universität Freiburg

Winter term 2004/2005

# Lectures: Where, When, Webpage

## Where

Lecture hall 52-02-017

## When

Wednesday 14:15–15:50, Friday: 14:15–15:00 (+ exercises)

## Christmas break

Last lecture before Christmas: Wednesday, December 22

First lecture after Christmas: Friday, January 7

## Web page

<http://www.informatik.uni-freiburg.de/~ki/teaching/ws0405/krr/>

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Time, location, web page

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# Lecturers

## Prof Dr. Bernhard Nebel

Room 52-00-028

Consultation: Tuesday 14:00-15:00 and by appointment

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## Dr. Jussi Rintanen

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## Dr. Stefan Wölfl

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## Where

Lecture hall 52-02-017

## When

Friday 15:05-15:50

**exercise assistant: Malte Helmert**

Room 52-00-030, Phone: 0761/203-8225  
email: [helmert@informatik.uni-freiburg.de](mailto:helmert@informatik.uni-freiburg.de)

### Organization

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### Motivation

- Exercises will be given at the web page on Wednesdays. (However, first exercise on Friday, October 22.)
- Solutions can be given in English and German.
- Students can work in pairs and hand in one solution.
- Larger groups and copied results will not be accepted.
- Previous week's exercises have to be handed in before the lecture on Wednesday.

- A written examination takes place in the semester pause.
- The examination is obligatory for *ACS Master* students.
- Grade:
  - max 100 points from the exam
  - max 10 bonus points from exercises
  - max 10 bonus points from projects (programming exercises)

# Course Prerequisites & Goals

## Goals

- Acquiring skills in representing knowledge
- Understanding the principles behind different knowledge representation techniques
- Being able to read and understand research literature in the area of KR&R
- Being able to complete a project in this research area

## Prerequisites

- Basic knowledge in the area of AI
- Basic knowledge in formal logic
- Basic knowledge in theoretical computer science

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# AI and Knowledge Representation

- **AI** can be described as: The study of **intelligent behavior** achieved through **computational means**
- **Knowledge representation and reasoning** could then be viewed as the study of how to **reason** (compute) with **knowledge** in order to decide what to do.
- Before we can start reasoning with knowledge, we have to **represent** it.

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- We understand by “knowledge” all kinds of facts about the world.
- Knowledge is necessary for intelligent behavior (human beings, robots).
- What is knowledge? We shall not try to answer this question!
- Instead, in this course we consider “representations of knowledge”.

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# Representation

- If **A** represents **B**, then **A** stands for **B** and is usually more easily accessible than **B**.
- In our case we are interested in **groups of symbols** that stand for some **proposition**.

## Knowledge Representation

The field of study concerned with **representations** of propositions (that are believed by some agent)

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- **Reasoning** is the use of representations of propositions in order to derive new ones.
- While propositions are abstract objects, their representations are concrete objects and can be easily manipulated.
- Reasoning can be as easy as arithmetics  $\rightsquigarrow$  mechanical symbol manipulation.
- For example:
  - raining is true
  - IF raining is true THEN wet street is true
  - wet street is true

# Why is Knowledge Representation and Reasoning Useful?

- Describing/understanding the behavior of systems in terms of the knowledge it has.
- Generating the behavior of a system!
  - Declarative knowledge can be separated from its possible usages.  
(compare: procedural knowledge)
  - Understanding the behavior of an intelligent system in terms of the represented knowledge makes debugging and understanding much easier.
  - Modifications and extensions are also much easier to perform.

# Knowledge-Based Systems: An Example

```
printC(snow) :- !, write("It's white").
printC(grass) :- !, write("It's green").
printC(sky) :- !, write("It's yellow").
printC(X) :- !, write("Beats me").
```

---

```
printC(X) :- color(X,Y), !, write("It's "), write(Y).
printC(X) :- write("Beats me").
color(snow,white).
color(sky,yellow).
color(X,Y) :- madeof(X,Z), color(Z,Y).
madeof(grass,vegetation).
color(vegetation,green).
```

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# Advantages of Knowledge-Based Systems

- Why not use the first variant of the Prolog program?
- We can add new tasks and make them depend on previous knowledge.
- We can extend existing behavior by adding new facts.
- We can easily explain and justify the behavior.

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# Why Reasoning?

- Note: there was no **explicit** statement about the color of grass in the program.
- In general: many facts will be there only **implicitly**.
- Use concept of **entailment**/logical implication.
- Can/shall we compute all implicit (all entailed) facts?
- It may be computationally too expensive.

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# The Role of Formal Logic

- Formal logic is the field of study of entailment relations, formal languages, truth conditions, semantics, and inference.
- All propositions are represented as formulae which have a semantics according to the logic in question.
- Formal logics gives us a framework to discuss different kinds of reasoning.

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# Different Kinds of Reasoning

- Usually, we are interested in deriving implicit, entailed facts from a given collection of explicitly represented facts
  - in a **logically sound** (the derived proposition must be true, given that the premises are true)
  - and **complete** way (all true consequences can be derived)
- Sometimes, however, we want logically unsound derivations (e.g. reasoning based on assumptions.)
- Sometimes, we want to give up completeness (e.g. for efficiency reasons.)

# Model-Finding and Satisfiability

- In planning and configuration tasks, we often get a set of **constraints** and a goal specification. We then have to find a solution satisfying all the constraints.
  - Either round or square
  - Either red or blue
  - If red and round or if blue and square then wood
  - If blue then metallic
  - If square then not metallic
  - If red then square
  - square

One solution: square, not metallic, red, wood

- Does not logically follow, but is one possible assignment (or model).

# Abduction: Inference to the Best Explanation

- In diagnosis tasks, we often have to find a good **explanation** for a given **observation** or **symptom**.
- Given a background theory, a set of explanations and an observation, find the **most likely set of explanations**.
  - earthquake implies alarm
  - burglar implies alarm
  - { earthquake, burglar } is the set of abducibles
  - alarm is observed
  - One explanation is earthquake ...
- There can be many possible explanations.
- Not a sound inference

# Default Reasoning: Jumping to Conclusions

- Often we do not have enough information, but nevertheless want to reach a conclusion (that is likely to be true).
- In the absence of evidence to the contrary, we **jump to a conclusion**.
  - Birds are usually able to fly.
  - Tweety is a bird.
  - So, you would expect that Tweety is able to fly.
- Unsound conclusion
- It might be necessary to withdraw conclusions when evidence to the contrary becomes available  $\rightsquigarrow$  nonmonotonic reasoning.

# The Role of Complexity Theory (1)

- Intelligent behavior is based on a vast amount of knowledge: Reddy's (1988) estimate is 70000 knowledge "units".
- Because of the huge amount of knowledge we have represented, reasoning should be easy in the complexity theory sense.
- Reasoning should **scale** well: we need efficient reasoning algorithms.

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# The Role of Complexity Theory (2)

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Use complexity theory and recursion theory to

- determine the complexity of reasoning problems,
- compare and classify different approaches based on complexity results,
- identify easy (polynomial-time) special cases,
- use heuristics/approximations for provably hard problems, and
- choose among different approaches.

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- 1 Introduction
- 2 Reminder: Classical Logic
- 3 A New Logic: Boxes and Diamonds
- 4 Nonmonotonic Logics
- 5 Qualitative Spatial and Temporal Reasoning
- 6 Description Logics

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- R. J. Brachman and Hector J. Levesque, *Knowledge Representation and Reasoning*, unpublished manuscript.
- C. Beierle and G. Kern-Isberner, *Methoden wissensbasierter Systeme*, Vieweg, 2000.
- G. Brewka, ed., *Principles of Knowledge Representation*, CSLI Publications, 1996.
- G. Lakemeyer and B. Nebel (eds.), *Foundations of Knowledge Representation and Reasoning*, Springer-Verlag, 1994
- W. Bibel *Wissensrepräsentation und Inferenz*, Vieweg, 1993

# Literature II

- R. J. Brachman and Hector J. Levesque (eds.), *Readings in Knowledge Representation*, Morgan Kaufmann, 1985.
- B. Nebel, “Logics for Knowledge Representation,” in: N. J. Smelser and P. B. Baltes (eds.), *International Encyclopedia of the Social and Behavioral Sciences*, Kluwer, Dordrecht, 2001.
- B. Nebel, “Artificial Intelligence: A Computational Perspective” in G. Brewka, ed., *Principles of Knowledge Representation, Studies in Logic, Language and Information*, CSLI Publications, 1996, 237-266.
- *Proceedings of the International Conference on Principles of Knowledge Representation and Reasoning*, (1989, 1991, 1992, . . . , 2002, 2004), Morgan Kaufmann Publishers.

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