

# Abstraction

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## abstraction of $post$ by $post^\#$

- ▶ instead of iteratively applying  $post$ , use over-approximation  $post^\#$  such that always

$$post(\varphi, \rho) \models post^\#(\varphi, \rho)$$

- ▶ decompose computation of  $post^\#$  into two steps:  
first, apply  $post$  and then, over-approximate result
- ▶ define abstraction function  $\alpha$  such that always

$$\varphi \models \alpha(\varphi) .$$

- ▶ for a given abstraction function  $\alpha$ , define  $post^\#$ :

$$post^\#(\varphi, \rho) = \alpha(post(\varphi, \rho))$$

## abstraction of $\varphi_{reach}$ by $\varphi_{reach}^\#$

- ▶ instead of computing  $\varphi_{reach}$ , compute over-approximation  $\varphi_{reach}^\#$  such that  $\varphi_{reach}^\# \supseteq \varphi_{reach}$
- ▶ check whether  $\varphi_{reach}^\#$  contains any error states  
if  $\varphi_{reach}^\# \wedge \varphi_{err} \models false$   
then  $\varphi_{reach} \wedge \varphi_{err} \models false$ , i.e., program is safe
- ▶ compute  $\varphi_{reach}^\#$  by applying iteration

$$\begin{aligned}\varphi_{reach}^\# &= \alpha(\varphi_{init}) \vee \\ &\quad post^\#(\alpha(\varphi_{init}), \rho_{\mathcal{R}}) \vee \\ &\quad post^\#(post^\#(\alpha(\varphi_{init}), \rho_{\mathcal{R}}), \rho_{\mathcal{R}}) \vee \dots \\ &= \bigvee_{i \geq 0} (post^\#)^i(\alpha(\varphi_{init}), \rho_{\mathcal{R}})\end{aligned}$$

- ▶ consequence:  $\varphi_{reach} \models \varphi_{reach}^\#$

## predicate abstraction

- ▶ construct abstraction  $\alpha(\varphi)$  using a given set of building blocks, so-called predicates
- ▶ predicate = formula over the program variables  $V$
- ▶ fix finite set of predicates  $Preds = \{p_1, \dots, p_n\}$
- ▶ over-approximation of  $\varphi$  by conjunction of predicates in  $Preds$

$$\alpha(\varphi) = \bigwedge \{p \in Preds \mid \varphi \models p\}$$

- ▶ computation of  $\alpha(\varphi)$  requires  $n$  entailment checks ( $n =$  number of predicates)

example: compute  $\alpha(at\_l_2 \wedge y \geq z \wedge x + 1 \leq y)$

►  $Preds = \{at\_l_1, \dots, at\_l_5, y \geq z, x \geq y\}$

1. to compute  $\alpha(\varphi)$ , check logical consequence between  $\varphi$  and each of the predicates:

	$y \geq z$	$x \geq y$	$at\_l_1$	$at\_l_2$	$at\_l_3$	$at\_l_4$	$at\_l_5$
$at\_l_2 \wedge$							
$y \geq z \wedge$	$\models$	$\not\models$	$\not\models$	$\models$	$\not\models$	$\not\models$	$\not\models$
$x + 1 \leq y$							

2. result of abstraction = conjunction over entailed predicates

$$\alpha\left( \begin{array}{l} at\_l_2 \wedge \\ y \geq z \wedge x + 1 \leq y \end{array} \right) = at\_l_2 \wedge y \geq z$$

trivial abstraction  $\alpha(\varphi) = true$

- ▶ result of applying predicate abstraction is *true* if none of the predicates is entailed by  $\varphi$  (“predicates are too specific”)  
... always the case if  $Preds = \emptyset$

## algorithm ABSTREACH

**begin**

$\alpha := \lambda\varphi . \bigwedge\{p \in \text{Preds} \mid \varphi \models p\}$

$\text{post}^\# := \lambda(\varphi, \rho) . \alpha(\text{post}(\varphi, \rho))$

$\text{ReachStates}^\# := \{\alpha(\varphi_{\text{init}})\}$

$\text{Parent} := \emptyset$

$\text{Worklist} := \text{ReachStates}^\#$

**while**  $\text{Worklist} \neq \emptyset$  **do**

$\varphi := \text{choose from Worklist}$

$\text{Worklist} := \text{Worklist} \setminus \{\varphi\}$

**for each**  $\rho \in \mathcal{R}$  **do**

$\varphi' := \text{post}^\#(\varphi, \rho)$

**if**  $\varphi' \notin \text{ReachStates}^\#$  **then**

$\text{ReachStates}^\# := \{\varphi'\} \cup \text{ReachStates}^\#$

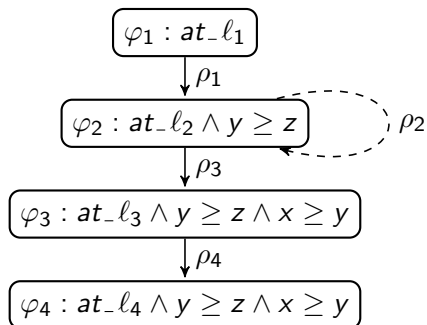
$\text{Parent} := \{(\varphi, \rho, \varphi')\} \cup \text{Parent}$

$\text{Worklist} := \{\varphi'\} \cup \text{Worklist}$

**return**  $(\text{ReachStates}^\#, \text{Parent})$

**end**

# Abstract Reachability Graph



$$\varphi_1 = \alpha(\varphi_{init})$$

$$\varphi_2 = post^\#(\varphi_1, \rho_1)$$

$$post^\#(\varphi_2, \rho_2) \models \varphi_2$$

$$\varphi_3 = post^\#(\varphi_2, \rho_3)$$

$$\varphi_4 = post^\#(\varphi_3, \rho_4)$$

- ▶  $Preds = \{false, at\_l_1, \dots, at\_l_5, y \geq z, x \geq y\}$
- ▶ nodes  $\varphi_1, \dots, \varphi_4 \in ReachStates^\#$
- ▶ labeled edges  $\in Parent$
- ▶ dotted edge : entailment relation (here,  $post^\#(\varphi_2, \rho_2) \models \varphi_2$ )



## example: predicate abstraction to compute $\varphi_{reach}^\#$

- ▶  $Preds = \{false, at\_l_1, \dots, at\_l_5, y \geq z, x \geq y\}$
- ▶ over-approximation of the set of initial states  $\varphi_{init}$ :

$$\varphi_1 = \alpha(at\_l_1) = at\_l_1$$

- ▶ apply  $post^\#$  on  $\varphi_1$  wrt. each program transition:

$$\varphi_2 = post^\#(\varphi_1, \rho_1) = \alpha(\underbrace{at\_l_2 \wedge y \geq z}_{post(\varphi_1, \rho_1)}) = at\_l_2 \wedge y \geq z$$

$$post^\#(\varphi_1, \rho_2) = \dots = post^\#(\varphi_1, \rho_5) = \bigwedge \{false, \dots\} = false$$

apply  $post^\#$  to  $\varphi_2 = (at\_l_2 \wedge y \geq z)$

- ▶ application of  $\rho_1$ ,  $\rho_4$ , and  $\rho_5$  on  $\varphi_2$  results in *false* (since  $\rho_1$ ,  $\rho_4$ , and  $\rho_5$  are applicable only if either  $at\_l_1$  or  $at\_l_3$  hold)
- ▶ for  $\rho_2$  we obtain

$$post^\#(\varphi_2, \rho_2) = \alpha(at\_l_2 \wedge y \geq z \wedge x \leq y) = at\_l_2 \wedge y \geq z$$

result is  $\varphi_2$  which is already in  $ReachStates^\#$ : nothing to do

- ▶ for  $\rho_3$  we obtain

$$\begin{aligned} post^\#(\varphi_2, \rho_3) &= \alpha(at\_l_3 \wedge y \geq z \wedge x \geq y) \\ &= at\_l_3 \wedge y \geq z \wedge x \geq y \\ &= \varphi_3 \end{aligned}$$

new node  $\varphi_3$  in  $ReachStates^\#$ , new edge in  $Parent$

apply  $post^\#$  to  $\varphi_3 = (at\_l_3 \wedge y \geq z \wedge x \geq y)$

- ▶ application of  $\rho_1$ ,  $\rho_2$ , and  $\rho_3$  on  $\varphi_3$  results in *false*
- ▶ for  $\rho_4$  we obtain:

$$\begin{aligned} post^\#(\varphi_3, \rho_4) &= \alpha(at\_l_4 \wedge y \geq z \wedge x \geq y \wedge x \geq z) \\ &= at\_l_4 \wedge y \geq z \wedge x \geq y \\ &= \varphi_4 \end{aligned}$$

new node  $\varphi_4$  in  $ReachStates^\#$ , new edge in  $Parent$

- ▶ for  $\rho_5$  (assertion violation) we obtain:

$$\begin{aligned} post^\#(\varphi_3, \rho_5) &= \alpha(at\_l_5 \wedge y \geq z \wedge x \geq y \wedge x + 1 \leq z) \\ &= false \end{aligned}$$

- ▶ any further application of program transitions does not compute any additional reachable states
- ▶ thus,  $\varphi_{reach}^\# = \varphi_1 \vee \dots \vee \varphi_4$
- ▶ since  $\varphi_{reach}^\# \wedge at\_l_5 \models false$ , the program is proven safe

# abstraction $\alpha(\varphi)$

- ▶ monotonicity

$$\varphi_1 \models \varphi_2 \text{ implies } \alpha(\varphi_1) \models \alpha(\varphi_2)$$

- ▶ idempotency

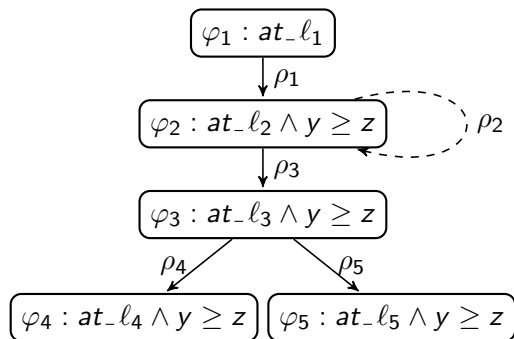
$$\alpha(\alpha(\varphi_1)) = \alpha(\varphi_1)$$

- ▶ extensiveness

$$\varphi_1 \models \alpha(\varphi_1)$$

# Abstract reachability computation with

$Preds = \{false, at\_l_1, \dots, at\_l_5, y \geq z\}$



$$\varphi_1 = \alpha(\varphi_{init})$$

$$\varphi_2 = post^\#(\varphi_1, \rho_1)$$

$$post^\#(\varphi_2, \rho_2) \models \varphi_2$$

$$\varphi_3 = post^\#(\varphi_2, \rho_3)$$

$$\varphi_4 = post^\#(\varphi_3, \rho_4)$$

$$\varphi_5 = post^\#(\varphi_3, \rho_5)$$

- ▶ omitting just one predicate (in the example:  $x \geq y$ ) may lead to an over-approximation  $\varphi_{reach}^\#$  such that

$$\varphi_{reach}^\# \wedge \varphi_{err} \not\equiv false$$

that is, ABSTREACH without the predicate  $x \geq y$  fails to prove safety

## counterexample path

- ▶ *Parent* relation records sequence leading to  $\varphi_5$ 
  - ▶ apply  $\rho_1$  to  $\varphi_1$  and obtain  $\varphi_2$
  - ▶ apply  $\rho_3$  to  $\varphi_2$  and obtain  $\varphi_3$
  - ▶ apply  $\rho_5$  to  $\varphi_3$  and obtain  $\varphi_5$
- ▶ counterexample path:  
sequence of program transitions  $\rho_1$ ,  $\rho_3$ , and  $\rho_5$
- ▶ Using this path and the functions  $\alpha$  and  $post^\#$  corresponding to the current set of predicates we obtain

$$\varphi_5 = post^\#(post^\#(post^\#(\alpha(\varphi_{init}), \rho_1), \rho_3), \rho_5)$$

that is,  $\varphi_5$  is equal to the over-approximation of the post-condition computed along the counterexample path

## analysis of counterexample path

- ▶ check if the counterexample path also leads to the error states when no over-approximation is applied
- ▶ compute

$$\begin{aligned} & post(post(post(\varphi_{init}, \rho_1), \rho_3), \rho_5) \\ &= post(post(at\_l_2 \wedge y \geq z, \rho_3), \rho_5) \\ &= post(at\_l_3 \wedge y \geq z \wedge x \geq y, \rho_5) \\ &= false . \end{aligned}$$

- ▶ by executing the program transitions  $\rho_1$ ,  $\rho_3$ , and  $\rho_5$  is not possible to reach any error
- ▶ conclude that the over-approximation is too coarse when dealing with the above path



## need for refinement of abstraction

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## need for refinement of abstraction

- ▶ need a more precise over-approximation that will prevent  $\varphi_{reach}^\#$  from including error states
- ▶ need a more precise over-approximation that will prevent  $\alpha$  from including states that lead to error states along the path  $\rho_1$ ,  $\rho_3$ , and  $\rho_5$
- ▶ need a refined abstraction function  $\alpha$  and a corresponding  $post^\#$  such that the execution of `ABSTRACTREACH` along the counterexample path does not compute a set of states that contains some error states

$$post^\#(post^\#(post^\#(\alpha(\varphi_{init}), \rho_1), \rho_3), \rho_5) \wedge \varphi_{err} \models false .$$

## over-approximation along counterexample path

- ▶ goal:

$$post^\#(post^\#(post^\#(\alpha(\varphi_{init}), \rho_1), \rho_3), \rho_5) \wedge \varphi_{err} \models false .$$

- ▶ define sets of states  $\psi_1, \dots, \psi_4$  such that

$$\varphi_{init} \models \psi_1$$

$$post(\psi_1, \rho_1) \models \psi_2$$

$$post(\psi_2, \rho_3) \models \psi_3$$

$$post(\psi_3, \rho_5) \models \psi_4$$

$$\psi_4 \wedge \varphi_{err} \models false$$

- ▶ thus,  $\psi_1, \dots, \psi_4$  guarantee that no error state can be reached  
may approximate / still allow additional states
- ▶ example choice for  $\psi_1, \dots, \psi_4$

$\psi_1$	$\psi_2$	$\psi_3$	$\psi_4$
$at\_l_1$	$at\_l_2 \wedge y \geq z$	$at\_l_3 \wedge x \geq z$	$false$

## refinement of predicate abstraction

- ▶ given sets of states  $\psi_1, \dots, \psi_4$  such that

$$\varphi_{init} \models \psi_1$$

$$post(\psi_1, \rho_1) \models \psi_2$$

$$post(\psi_2, \rho_3) \models \psi_3$$

$$post(\psi_3, \rho_5) \models \psi_4$$

$$\psi_4 \wedge \varphi_{err} \models false$$

- ▶ add  $\psi_1, \dots, \psi_4$  to the set of predicates  $Preds$
- ▶ formal property (discussed later) guarantees:

$$\alpha(\varphi_{init}) \models \psi_1$$

$$post^\#(\psi_1, \rho_1) \models \psi_2$$

$$post^\#(\psi_2, \rho_3) \models \psi_3$$

$$post^\#(\psi_3, \rho_5) \models \psi_4$$

$$\psi_4 \wedge \varphi_{err} \models false$$

proves: no error state reachable along path  $\rho_1, \rho_3$ , and  $\rho_5$

next ...

- ▶ approach for analysing counterexample computed by `ABSTRACTREACH`
- ▶ algorithms `MAKEPATH`, `FEASIBLEPATH`, and `REFINEPATH`

# path computation

**function** MAKEPATH

**input**

$\psi$  - reachable abstract state

$Parent$  - predecessor relation

**begin**

1  $path :=$  empty sequence

2  $\varphi' := \psi$

3 **while** exist  $\varphi$  and  $\rho$  such that  $(\varphi, \rho, \varphi') \in Parent$  **do**

4  $path := \rho . path$

5  $\varphi' := \varphi$

6 **return**  $path$

**end**

## path computation

- ▶ input: reachable abstract state  $\psi$  + *Parent* relation
- ▶ view *Parent* as a tree where  $\psi$  occurs as a node
- ▶ output: sequence of program transitions that labels the tree edges on path from root to  $\psi$
- ▶ sequence is constructed iteratively by a backward traversal starting from the input node
- ▶ variable *path* keeps track of the construction
- ▶ in example, call MAKEPATH( $\varphi_5$ , *Parent*)
- ▶ *path*, initially empty, is extended with transitions  $\rho_5$ ,  $\rho_3$ ,  $\rho_1$
- ▶ corresponding edges:  $(\varphi_3, \rho_5, \varphi_5)$ ,  $(\varphi_2, \rho_3, \varphi_3)$ ,  $(\varphi_1, \rho_1, \varphi_1)$
- ▶ output:  $path = \rho_1\rho_3\rho_5$



## feasibility of a path

**function** FEASIBLEPATH

**input**

$\rho_1 \dots \rho_n$  - path

**begin**

1  $\varphi := \text{post}(\varphi_{\text{init}}, \rho_1 \circ \dots \circ \rho_n)$

2 **if**  $\varphi \wedge \varphi_{\text{err}} \neq \text{false}$  **then**

3     **return** *true*

4 **else**

5     **return** *false*

**end**

## feasibility of a path

- ▶ input: sequence of program transitions  $\rho_1 \dots \rho_n$
- ▶ checks if there is a computation that produced by this sequence
- ▶ check uses the post-condition function and the relational composition of transition
- ▶ apply FEASIBLEPATH on example path  $\rho_1\rho_3\rho_5$
- ▶ relational composition of transitions yields

$$\rho_1 \circ \rho_3 \circ \rho_5 = \textit{false} .$$

- ▶ FEASIBLEPATH sets  $\varphi$  to *false* and then returns *false*

# counterexample-guided discovery of predicates

**function** REFINEPATH

**input**

$\rho_1 \dots \rho_n$  - path

**begin**

1  $\varphi_0, \dots, \varphi_n :=$  compute such that

2  $(\varphi_{init} \models \varphi_0) \wedge$

3  $(post(\varphi_0, \rho_1) \models \varphi_1) \wedge \dots \wedge (post(\varphi_{n-1}, \rho_n) \models \varphi_n) \wedge$

4  $(\varphi_n \wedge \varphi_{err} \models false)$

5 **return**  $\{\varphi_0, \dots, \varphi_n\}$

**end**

- ▶ omitted: particular algorithm for finding  $\varphi_0, \dots, \varphi_n$

## counterexample guided discovery of predicates

- ▶ input: sequence of program transitions  $\rho_1 \dots \rho_n$
- ▶ output: sets of states  $\varphi_0, \dots, \varphi_n$  such that
  - ▶  $\varphi_{init} \models \varphi_0$
  - ▶  $post(\varphi_{i-1}, \rho_i) \models \varphi_i$
  - ▶  $\varphi_n \wedge \varphi_{err} \models false$  for  $i \in 1..n$
- ▶ if  $\varphi_0, \dots, \varphi_n$  are added to *Preds* then the resulting  $\alpha$  and  $post^\#$  guarantee that

$$\alpha(\varphi_{init}) \models \varphi_0$$

$$post^\#(\varphi_0, \rho_1) \models \varphi_1$$

...

$$post^\#(\varphi_{n-1}, \rho_n) \models \varphi_n$$

$$\varphi_n \wedge \varphi_{err} \models false .$$

- ▶ in example, application of `REFINEPATH` on  $\rho_1\rho_3\rho_5$  yields sequence of sets of states  $\psi_1, \dots, \psi_4$

next ...

- ▶ algorithm for counterexample-guided abstraction refinement
- ▶ put together all building blocks into an algorithm `ABSTREFINELoop` that verifies safety using predicate abstraction and counterexample guided refinement

## predicate abstraction and refinement loop

```
function ABSTREFINELOOP
begin
1   Preds :=  $\emptyset$ 
2   repeat
3     (ReachStates#, Parent) := ABSTREACH(Preds)
4     if exists  $\psi \in \text{ReachStates}^\#$  such that  $\psi \wedge \varphi_{err} \neq \text{false}$ 
5   then
6     path := MAKEPATH( $\psi$ , Parent)
7     if FEASIBLEPATH(path) then
8       return "counterexample path: path "
9     else
10      Preds := REFINEPATH(path)  $\cup$  Preds
11  else
      return "program is correct"
end.
```

## algorithm `ABSTREFINELOOP`

- ▶ input: program, output: proof or counterexample
- ▶ compute  $\varphi_{reach}^\#$  using an abstraction defined wrt. set of predicates  $Preds$  (initially empty)
- ▶ over-approximation  $\varphi_{reach}^\#$  : set of formulas  $ReachStates^\#$  where each formula represents a set of states
- ▶ if set of error states disjoint from over-approximation: stop
- ▶ otherwise, consider a formula  $\psi$  in  $ReachStates^\#$  that witnesses overlap with error states
- ▶ refinement is only possible if overlap is caused by imprecision
- ▶ construct  $path$ , sequence of program transitions leading to  $\psi$
- ▶ analyze  $path$  using `FEASIBLEPATH`
- ▶ if  $path$  feasible: stop
- ▶ otherwise ( $path$  is not feasible), compute a set of predicates that refines the abstraction function

that's it!